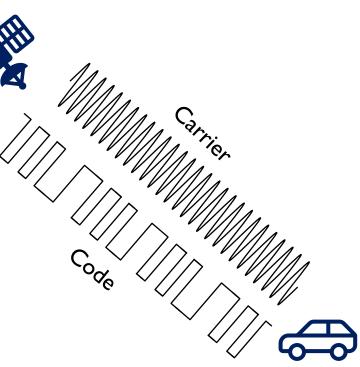
07: Signal Acquisition

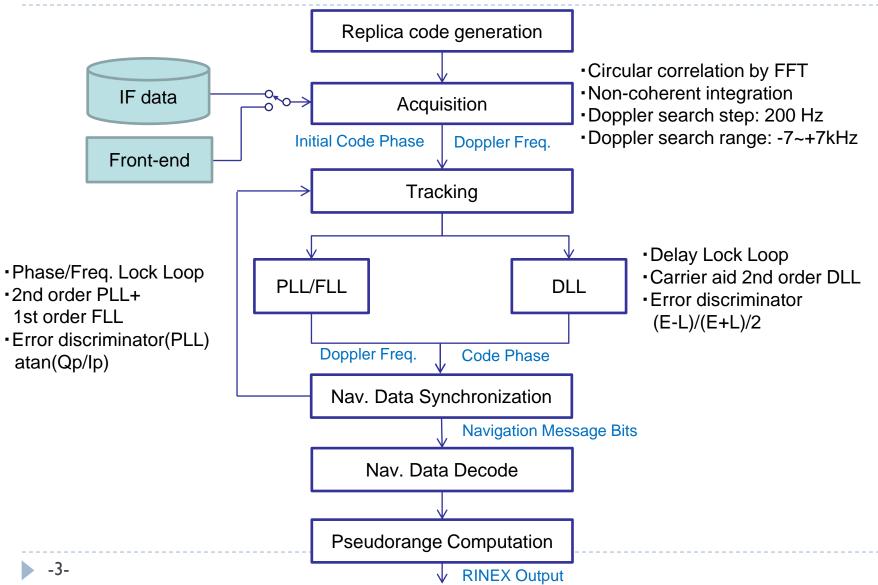
Taro Suzuki

Signal Acquisition

- Acquisition is to acquire the approximate code-phase and Doppler frequency of GNSS signals
- Tracking stage is difficult without acquisition information
- GNSS signal processing starts with signal acquisition



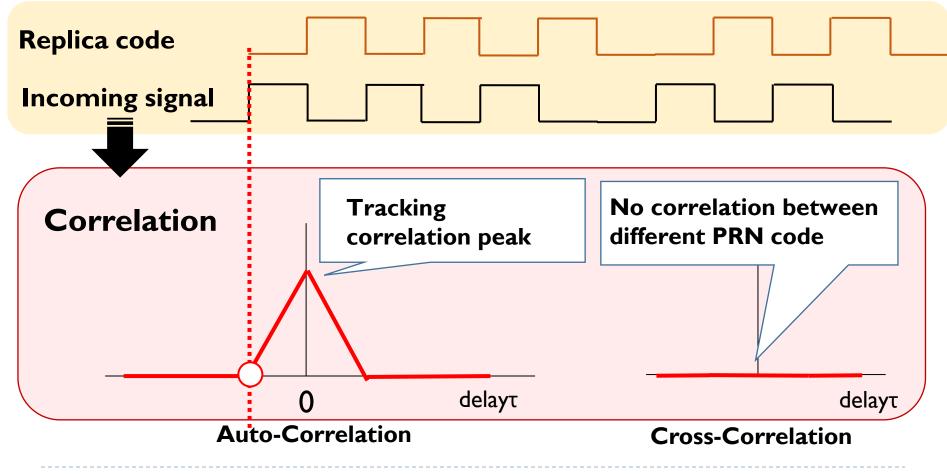
GNSS Signal Processing



GNSS Signal Correlation

(1) Replica PRN code generation

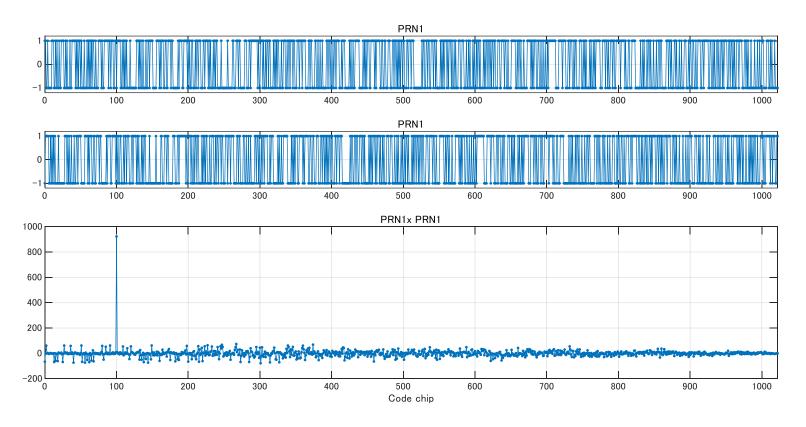
2 Correlation between replica code and incoming signal



Exercise 1: Auto/Cross-Correlation

MATLAB

/07_Signal_Acqusition/matlab/Exl_run_correlation.m

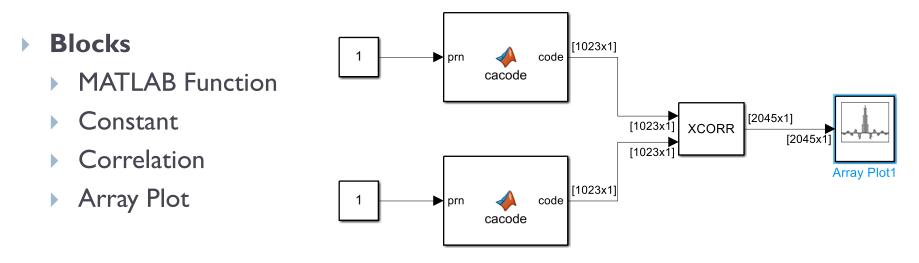


-5-

Exercise 2: Auto/Cross-Correlation

Simulink

/07_Signal_Acqusition/simulink/Ex2/correlation.slx



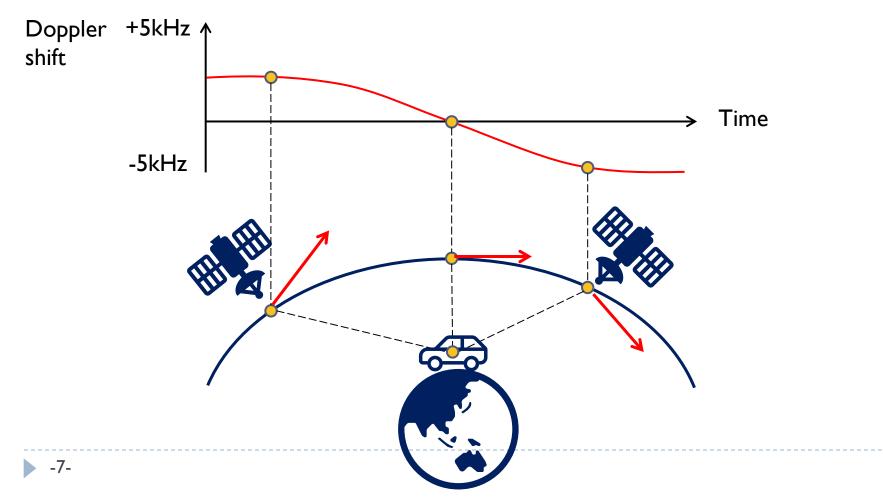
Advanced challenge

- Try reversing the sign of the code using <u>Gain</u>
- Magnitude of correlation outputs using <u>Magnitude Squared</u>
- Trim cross-correlation output using MATLAB Function

Doppler Frequency Shift

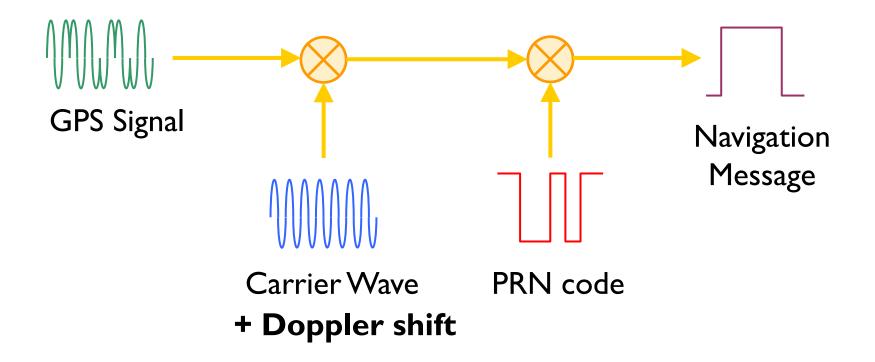
• Doppler frequency shift of approximately \pm 5kHz occurs

Satellite motion, Receiver motion, Satellite clock drift



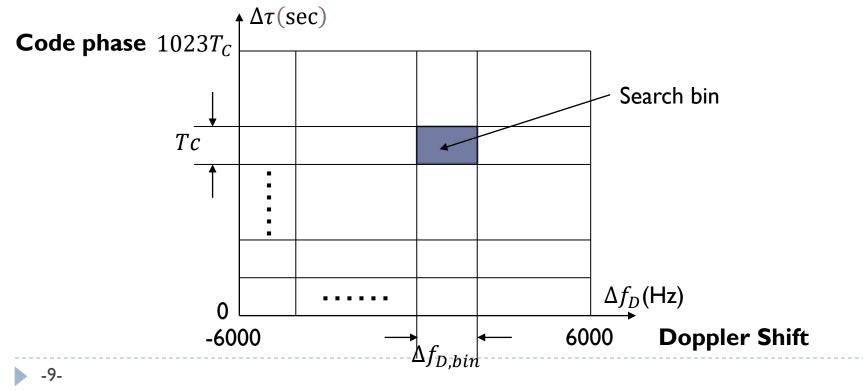
Carrier Wipe-off

- First carrier wipe-off and then correlate with the code
- Carrier contains Doppler frequency shift



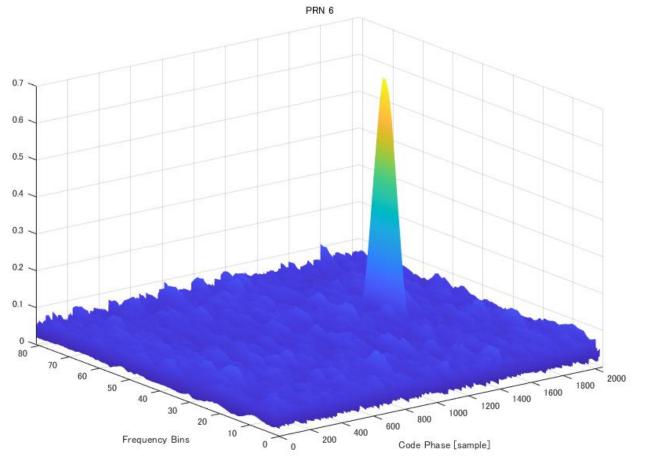
2D Search for Code Phase and Doppler

- Two things need to be estimated:
 - Doppler frequency shift and code phase
- High autocorrelation are obtained at the correct code phase and Doppler shift



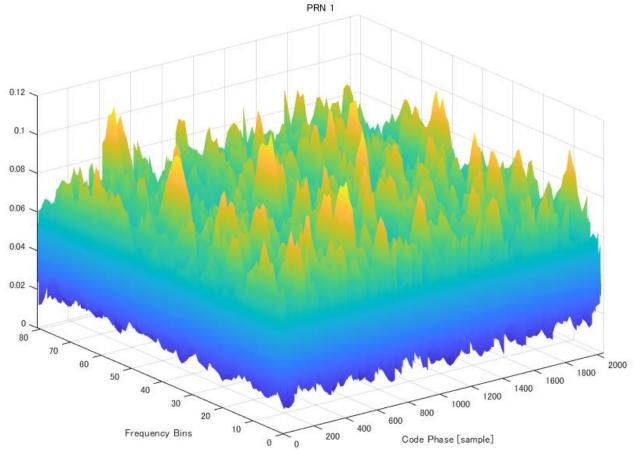
Example of Signal Acquisition (1)

Auto-correlation



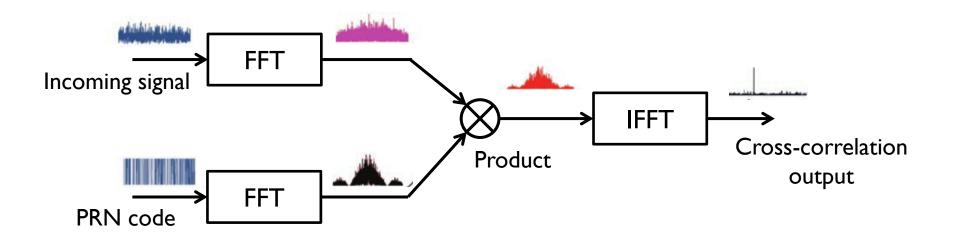
Example of Signal Acquisition (2)

Cross-correlation

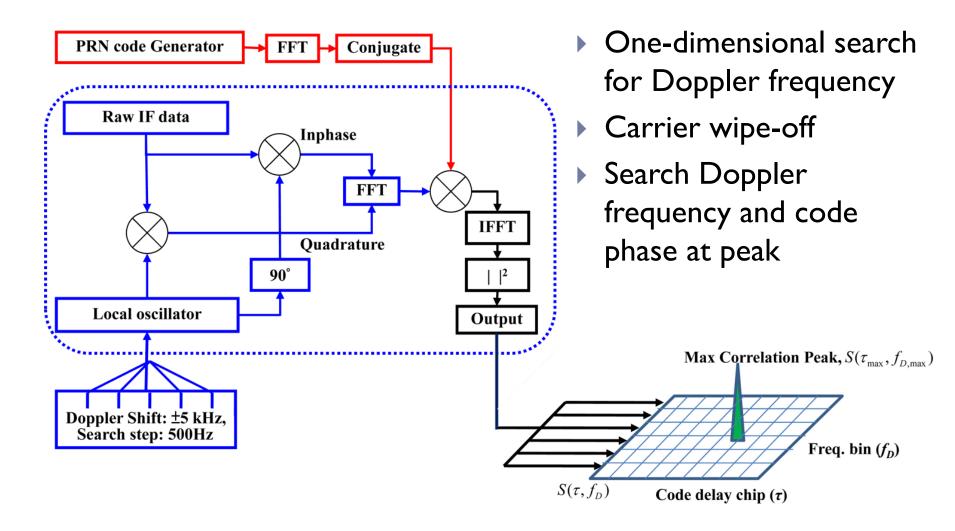


FFT-based Correlation (1)

- Circular correlation / Parallel search
- Depending on the data size, it is possible to compute cross-correlation quickly and efficiently
- Suitable for software receivers



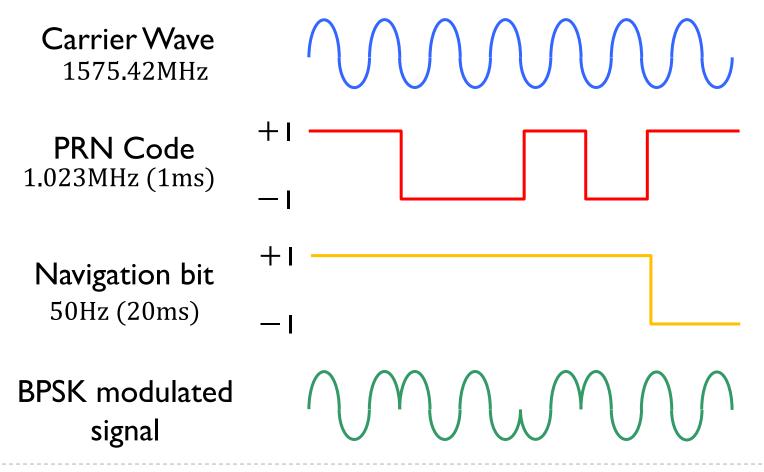
FFT-based Correlation (2)

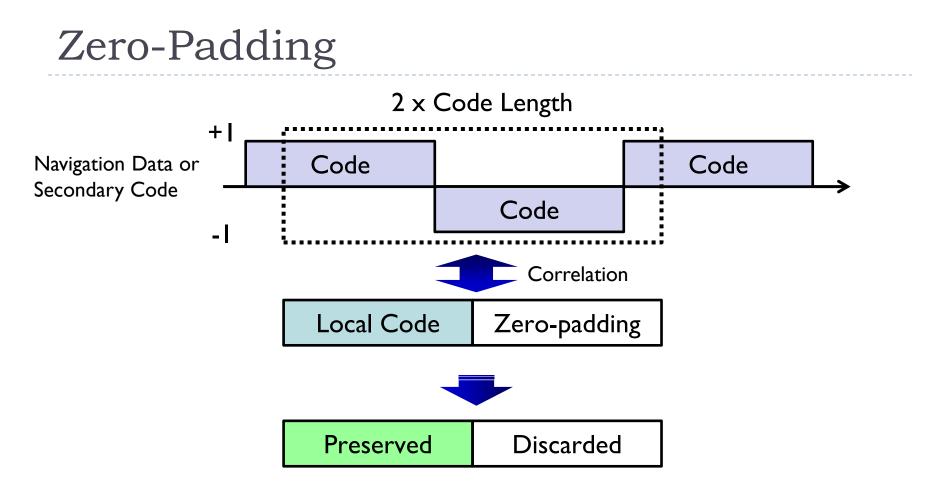


-13- Jan, S.-S.; Sun, C.-C. Signal Existence Verification (SEV) for GPS Low Received Power Signal Detection Using the Time-Frequency Approach. Sensors 2010

Navigation Bit Effect

Phase changes with navigation data bits





- Perfect correlation can be obtained when navigation bit is changed
- Computational cost is doubled

⁻¹⁵⁻ Ziedan, N. I., and Garrison, J. L. "Unaided acquisition of weak GPS signals using circular correlation or double-block zero padding"

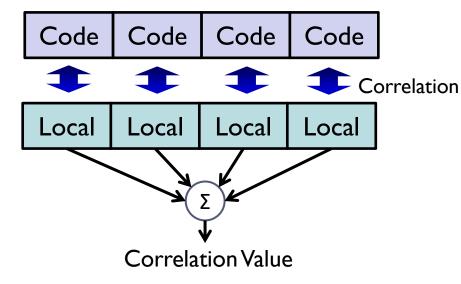
Integration

Coherent Integration Code Code Code Code Correlation Local Local Local Local

Correlation Value

- The coherent integration is a bandpass process
- Coherent integration increases sensitivity
- Navigation bit problem

Non-Coherent Integration

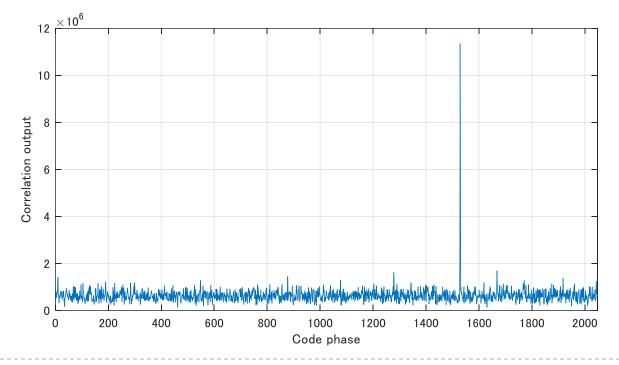


- Less sensitivity because of square loss
- Minimal effect on the phase of the navigation data bits

Exercise 3: Signal Acquisition

MATLAB

- /07_Signal_Acqusition/matlab/Ex3_run_acquisition_ID.m
- Change integration time
- Change Doppler frequency

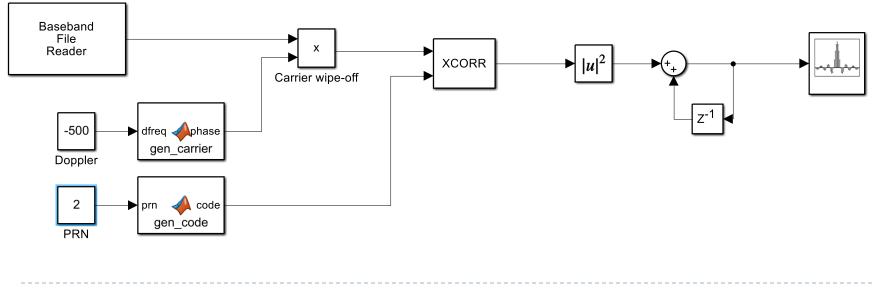


Exercise 4: Signal Acquisition

Simulink

- /07_Signal_Acquisition/simulink/Ex4/acquisition_ID.slx
- Blocks

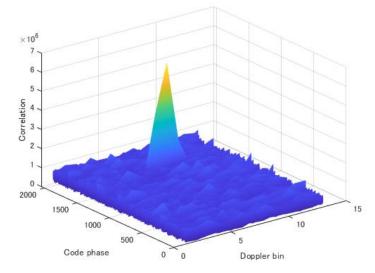
Product, Sum, Delay



Exercise 5: Signal Acquisition

MATLAB

- /07_Signal_Acqusition/matlab/Ex5_run_acquisition_2D.m
- Change Doppler search range/step

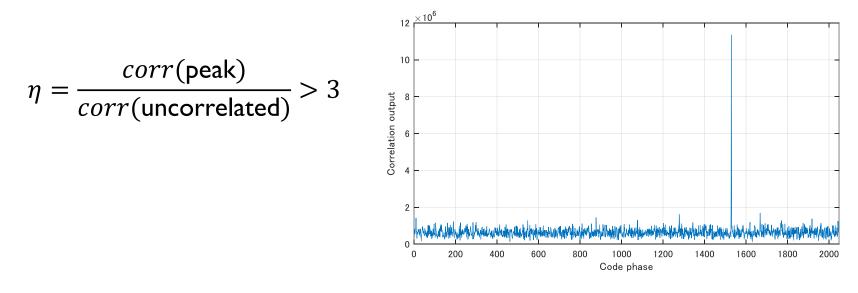


Advanced challenge

Try to acquired low-elevation satellite signal

Determination of Signal Acquisition

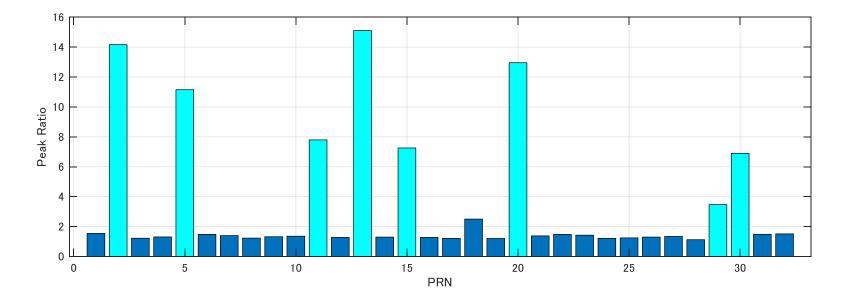
- In the case of a cold start, it must be determined whether the RF signal contains a certain satellite signal
- Signal acquisition (2-D search) to check for the presence of correlation peaks
- Ratio of peak to uncorrelated value



Exercise 6: Signal Acquisition

MATLAB

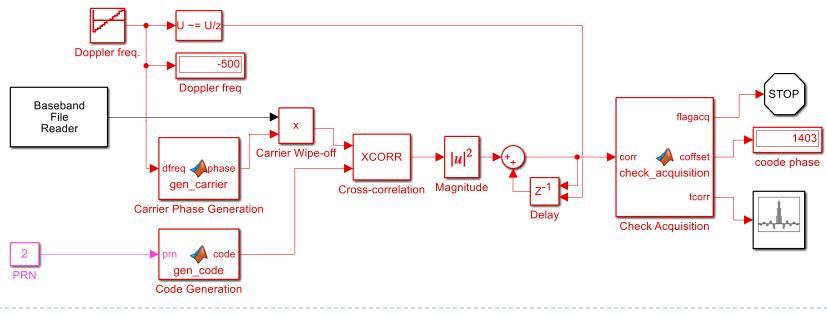
- /07_Signal_Acqusition/matlab/Ex6_run_acquisition_2D.m
- Two-dimensional search + Multiple PRN search
- Determination signal acquisition



Exercise 7: Signal Acquisition

Simulink

- /07_Signal_Acqusition/simulink/Ex7/correlation.slx
- Using parameter file
- Blocks
 - Repeating Sequence Stair, Detect Change, Stop Simulation



Type of Acquisition

Cold Start

- Start with no prior information whatsoever
- Signal acquisition of all satellites
- Decode navigation messages (minimum 30 seconds)

Warm start

- GNSS device remembers last position, almanac, and time
- Not which satellites were in view
- Decode navigation messages (minimum 30 seconds)

Reacquisition / Hot start

- Signal tracking has gone off
- Initial Doppler frequency and code phase are estimated

Signal Re-acquisition

- One satellite is temporarily blocked by an obstacle
 - Signal tracking is lost
- Receiver stores position, time, etc.
- Search around the chord phase and Doppler frequency at the time the signal is lost
- Loop lock indicator (LLI)
 - Monitor signal tracking status
 - If the signal is not tracked, it will be reacquisition.

